

DEXTER



ARTICULATED 6 AXIS ROBOT

PERFORMANCE

Payload Capacity: 5/10/20 Kg

Tip Speed: 1 Meter/ Second
Motion Precision: 100 Microns

Axes : 6

Reach : 1000 mm[5kg], 1300 mm[10 kg], 1500 mm [20 kg]

SPECIFICATIONS

Motion Range: Base: ± 360° Shoulder: ± 180° Elbow: ± 180° Forearm: ± 180° Wrist 1: ± 180° Wrist 2: ± 360°

POWER

Power Consumption : 200W [Typical], 600W [Max] Power On IO Ports/ TCP : 50W Signal Output : Profibus

IO Ports : 9 [3 Ana Out] [3 Digital In][3 Digital Out]

SAFETY

Torque Limit : All Joints Al Camera : Optional - 3D Sensing Around

Impact Sensor: Tool Center PointE-Stop: 2xSafety Curtains: OptionalImpact Sensor : 1x

TEACH PENDANT

On Board Computer : Intel Screen : 10 Inch

Motion Control : Grid-Motion Software
Aux Controller : ARM-32 Bit - Inbuilt

ENVIRONMENTAL

IP RATING : 50

Temperature : 0-60 Degrees

Humidity : 95% , Non-Condensing





DOMES

RAPINOV

TWIN ARM - PRECISION SCARA ROBOT

PERFORMANCE

Payload Capacity : 1/3/5 Kg

Tip Speed : 1 Meter/ Second
Motion Precision : 100 Microns

Axes : 4

Reach : 250 mm[1kg], 450 mm[3 kg], 600 mm [5 kg]

SPECIFICATIONS

Motion Range: Base Joints: ± 100° Vertical Motion: 200 mm Wrist: ± 360°

POWER

io Ports : 9 [3 Ana Out] [3 Digital In][3 Digital Out]

SAFETY

Torque Limit : All Joints Al Camera : Optional - 3D Sensing Around

Impact Sensor : Tool Center Point E-Stop : 2x Safety Curtains : Optional Impact Sensor : 1x

TEACH PENDANT

On Board Computer : Intel Screen : 10 Inch

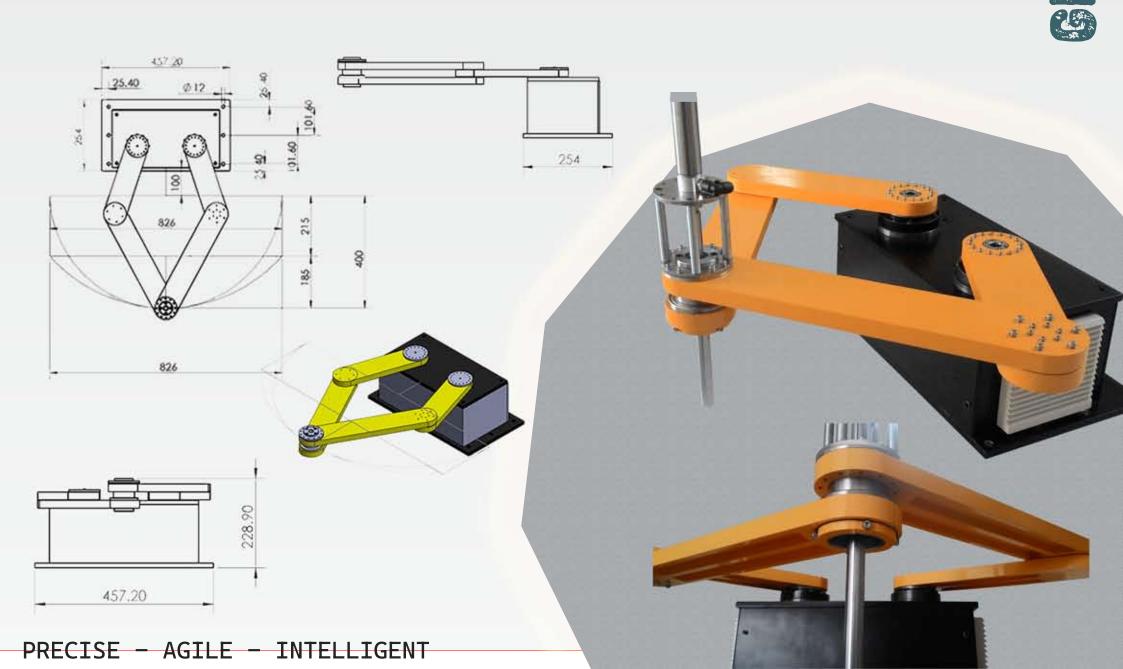
Motion Control : Grid-Motion Software
Aux Controller : ARM-32 Bit - Inbuilt

ENVIRONMENTAL

IP RATING : 50

Temperature : 0-60 Degrees

Humidity : 95% , Non-Condensing





William In



HIGH SPEED DELTA ROBOTS

PERFORMANCE

Tip Speed : 1 Meter/ Second Payload Capacity: 1/3/5 Kg : 100 Microns **Motion Precision**

Axes

Reach : 250 mm[1kg], 450 mm[3 kg], 600 mm [5 kg]

SPECIFICATIONS

IP Rating : 35 **Noise Levels** : 70 dB **Built Material** : Mild Steel **Robot Weight** : 25 Kg **Paint/Coating** : Powder Coating **Controller Box** : 15 Kg Weight [400x400x500 mm]

Motion Range: Base Joints: ± 100° Vertical Motion: 200 mm Wrist: ± 360°

POWER

Power On IO Ports/TCP: 50W : 200W [Typical] , 600W [Max] **Power Consumption Signal Output** : Profibus : 24/48 V DC **Motor Voltages**

IO Ports : 9 [3 Ana Out] [3 Digital In][3 Digital Out]

SAFETY

Torque Limit : All Joints **Al Camera** : Optional - 3D Sensing Around

300

115

Impact Sensor : Tool Center Point E-Stop : 2x **Safety Curtains** : Optional **Impact Sensor: 1x**

TEACH PENDANT

On Board Computer: Intel : 10 Inch Screen

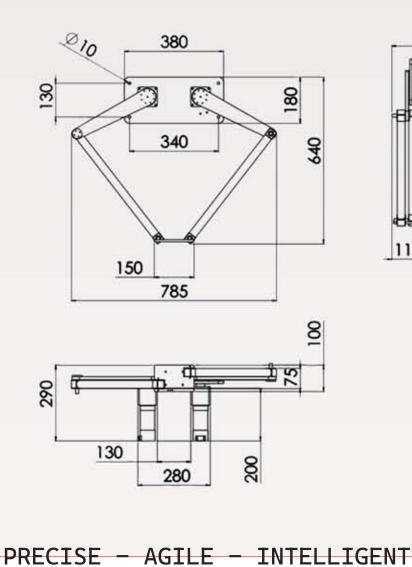
Motion Control : Grid-Motion Software **Aux Controller** : ARM-32 Bit - Inbuilt

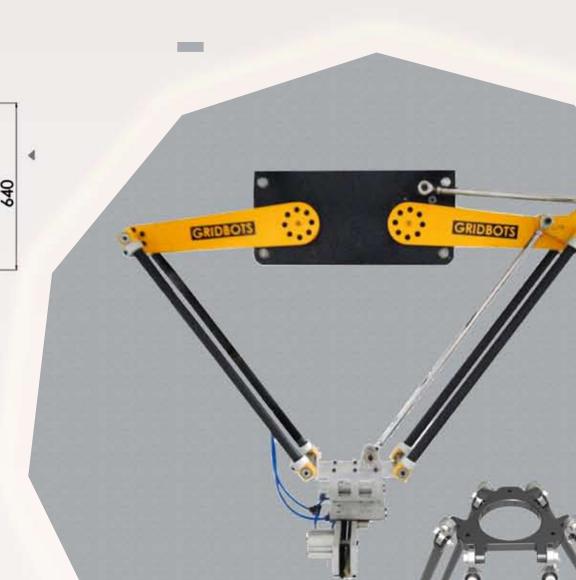
ENVIRONMENTAL

IP RATING : 50

Temperature : 0-60 Degrees

Humidity : 95%, Non-Condensing





THE COMPANY >>>

We are a Technology company from India and work in the field of Robotics - Artificial Intelligence and Machine Vision.

Founded in August 2007 by young and passionate innovator Mr. Pulkit Gaur [TED Fellow and MIT Young Innovator of the year].

We today are a team of more than 50 people-Head quartered in Ahmedabad and having offices in Pune and Delhi.

We design and develop ultra high performance systems which are used in the industry for defect detection - dimension measurement - sorting applications - grading application and many other ways. With our machine vision and robotic solutions we are helping our clients achieve digital factory goals in a time bound manner.

We would be glad to hear about your industry 4.0 adaptation strategy and would love to get in touch with you to explore the synergies in working together!

