

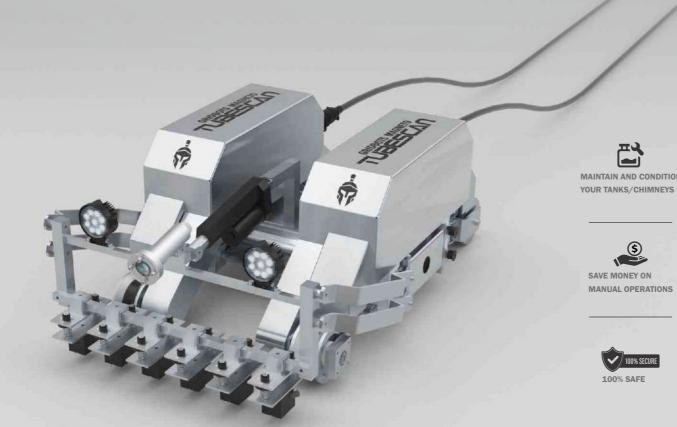
MAGNETO TUBESCAN WATERWALL ROBOT

Gridbots Magneto tubescan series of robots are designed to be used in vertical and inclined waterwalls of powerplant boilers.

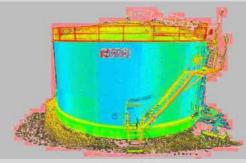
It has the capabilities to climb almost all kind of magnetic surfaces with a payload upto 50 kgs in most extreme temperature and surface conditions. The robot can be used for surface inspection, weld inspection, blasting, painting, coating, grinding, lapping or many other operations where it is difficult for a human worker to reach. The robot is ultra light construction from aircraft grade aluminum and high strength magnets to adhere to the surface with active distance compensation force multipliers underneath the body.

The robot is internally powered by strong PMSM geared motors, pedometer and 6 DOF IMU sensor to track the motion in all 6 DOF. It also features distance offset sensor beneath its surface to keep a constant distance maintained from the surface.

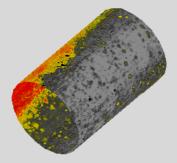
The robot has an array of 10 EMAT/USONIC sensors to measure the tube thickness and report it in real-time to the base computer- where a depth profile of pipes can be composed for later analysis



BOILER WATER-WALLS/ TANK WALL THICKNESS ASSESSMENT



TANK THICKNESS 3D PROFILE



PIPE THICKNESS 3D PROFILE



VARIANTS

Power Drive			S S
Twin 400Watts PMS Motors			Э
Adhesion Permanent Magnets			R 2
Tube Thickness Sensing Using Ultrasonic Probes (Upto 8 Channels in Single Broom)			RU
Robot Lines Speed Upto 20 mm/second			S V
Laser Scanner Coverage Width 150 mm			C U
Robot Power Consumption 100 W			0 1
SAFETY			
TOF Sensors 6x	lmpa 1x	ict S	ens

ENVIRONMENTAL

IP Rating 54

Temperature 5°C to 65°C





MAGNETO TUBESCAN

CONTROL UNIT

3D LASER PROFILOMETER



Robot Self Weight 0 Kgs

Robot Adhesion Force pto 500N

supply and Sensor Interfacing to the Robot ia Umbilical Cable

Cable Length pto 250 Meters

perator Control Unit 2" Touch Screen Tablet PC

E-Stop **2**x

> Humidity 95%, Non-Condensing





ULTRASONIC SENSORS

MFL SENSOR

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